HOMEWORK/LAB TEST #3

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Fall 2011

Tuning and operating servo hydraulic actuators

Scope: (a) Tune and operate a servo-controlled seismic actuator; (b) Evaluate a column specimen in elastic (and inelastic range)

- a) Determine all components required to operate an actuator (see diagram)
 - 01) Actuator components (<u>cylinder</u>, <u>alternative servovalve controller</u>, <u>load cell</u> + calibration sheet, displacement transducer + calibration sheet, *FlexTest Controller*)
 - 02) *Program initiation*: manual, ramps, sinusoidal, square **set program to square sine**
 - 03) *Establish feedback:* first: **displacement** and second: **force** transducer **zero position using set point**
 - 04) Identify error signal: set error to zero before turning power
 - 05) Determine limits: set limits for both force and displacement
 - 06) Hydraulic Power controller low, high, program, emergency stop power system
- b) Tune actuator first with displacement feedback, then second with force feedback
 - 01) Adjust (in this order) **P**, **I**, **D** and **F** gains, if necessary. See <u>practical notes</u>
 - 02) Observe actuator response (record screens showing the tuning).
 - 03) Record final settings of P, I, D and F gains
- c) Test the column after tuning the actuator using 3 cycles of "saw-tooth" sine using amplitude of .2 in or 1.0 Kips. Evaluate the force displacement diagram using:
 - 01) Displacement control using amplitude of .2 in
 - 02) Force control using amplitude of 1.0 Kips.
- d) For extra points: Develop a model for the actuator using the theoretical formulation using Matlab or equivalent. Simulate the operation of the actuator with various parameters. Compare calculated with observed.
- e) For extra points answer the following question: Check the sensitivity of the testing using the model of the actuator. Can the model of the actuator help in getting identical results from force and displacement controls?

Reference:

MTS FlexTest GT, Model 793 System Software

Note: Prepare report according to standard outline Due date: 2011-11-01 (111101)